Submodular Functions, Optimization, and Applications to Machine Learning
— Spring Quarter, Lecture 12 —

http://www.ee.washington.edu/people/faculty/bilmes/classes/ee563_spring_2018/

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\[ f(A) + f(B) \geq f(A \cup B) + f(A \cap B) \]

\[ = f(A) + 2f(C) + f(B) \]

\[ = f(A \setminus B) + f(B \setminus A) \]

Clockwise from top left:
- László Lovász
- Jack Edmonds
- Satoru Fujishige
- George Nemhauser
- Laurence Wolsey
- András Frank
- Lloyd Shapley
- H. Narayanan
- Robert Bixby
- William Cunningham
- William Tutte
- Richard Rado
- Alexander Schrijver
- Garrett Birkhoff
- Hassler Whitney
- Richard Dedekind
Cumulative Outstanding Reading

- Read chapter 1 from Fujishige’s book.
- Read chapter 2 from Fujishige’s book.
- Read chapter 3 from Fujishige’s book.
- Read chapter 4 from Fujishige’s book.
Announcements, Assignments, and Reminders

- Next homework is posted on canvas. Due Thursday 5/10, 11:59pm.
- As always, if you have any questions about anything, please ask then via our discussion board (https://canvas.uw.edu/courses/1216339/discussion_topics). Can meet at odd hours via zoom (send message on canvas to schedule time to chat).
Class Road Map - EE563

L1(3/26): Motivation, Applications, & Basic Definitions,
L3(4/2): Info theory exs, more apps, definitions, graph/combinatorial examples
L4(4/4): Graph and Combinatorial Examples, Matrix Rank, Examples and Properties, visualizations
L5(4/9): More Examples/Properties/Other SubmodularDefs., Independence,
L6(4/11): Matroids, Matroid Examples, Matroid Rank, Partition/Laminar Matroids
L7(4/16): Laminar Matroids, System of Distinct Reps, Transversals, Transversal Matroid, Matroid Representation, Dual Matroids
L8(4/18): Dual Matroids, Other Matroid Properties, Combinatorial Geometries, Matroids and Greedy.
L9(4/23): Polyhedra, Matroid Polytopes, Matroids $\rightarrow$ Polymatroids
L10(4/29): Matroids $\rightarrow$ Polymatroids, Polymatroids, Polymatroids and Greedy,
L11(4/30): Polymatroids, Polymatroids and Greedy
L12(5/2):
L13(5/7):
L14(5/9):
L15(5/14):
L16(5/16):
L17(5/21):
L18(5/23):
L–(5/28): Memorial Day (holiday)
L19(5/30):

Last day of instruction, June 1st. Finals Week: June 2-8, 2018.
Vector rank, $\text{rank}(x)$, is submodular

- Recall that the matroid rank function is submodular.
- The vector rank function $\text{rank}(x)$ also satisfies a form of submodularity, namely one defined on the real lattice.

**Theorem 12.2.1 (vector rank and submodularity)**

Let $P$ be a polymatroid polytope. The vector rank function $\text{rank} : \mathbb{R}_+^E \to \mathbb{R}$ with $\text{rank}(x) = \max \{y(E) : y \leq x, y \in P\}$ satisfies, for all $u, v \in \mathbb{R}_+^E$

$$\text{rank}(u) + \text{rank}(v) \geq \text{rank}(u \lor v) + \text{rank}(u \land v)$$ (12.1)
Theorem 12.2.1

A polymatroid can equivalently be defined as a pair \((E, P)\) where \(E\) is a finite ground set and \(P \subseteq \mathbb{R}_+^E\) is a compact non-empty set of independent vectors such that

1. every subvector of an independent vector is independent (if \(x \in P\) and \(y \leq x\) then \(y \in P\), i.e., down closed)
2. If \(u, v \in P\) (i.e., are independent) and \(u(E) < v(E)\), then there exists a vector \(w \in P\) such that

\[
u < w \leq u \lor v\quad (12.20)
\]

Corollary 12.2.2

The independent vectors of a polymatroid form a convex polyhedron in \(\mathbb{R}_+^E\).
More on polymatroids

For any compact set $P$, $b$ is a base of $P$ if it is a maximal subvector within $P$. Recall the bases of matroids. In fact, we can define a polymatroid via vector bases (analogous to how a matroid can be defined via matroid bases).

Theorem 12.2.1

A polymatroid can equivalently be defined as a pair $(E, P)$ where $E$ is a finite ground set and $P \subseteq \mathbb{R}^E_+$ is a compact non-empty set of independent vectors such that

1. every subvector of an independent vector is independent (if $x \in P$ and $y \leq x$ then $y \in P$, i.e., down closed)
2. if $b, c$ are bases of $P$ and $d$ is such that $b \wedge c < d < b$, then there exists an $f$, with $d \wedge c < f \leq c$ such that $d \vee f$ is a base of $P$
3. All of the bases of $P$ have the same rank.

Note, all three of the above are required for a polymatroid (a matroid analogy would require the equivalent of only the first two).
Considering Theorem ??, the matroid case is now a special case, where we have that:

**Corollary 12.2.2**

\[
\max \{ y(E) : y \in P_{\text{ind. set}}(M), y \leq x \} = \min \{ r_M(A) + x(E \setminus A) : A \subseteq E \} 
\]

where \( r_M \) is the matroid rank function of some matroid.
Polymatroidal polyhedron and greedy

Let \((E, \mathcal{I})\) be a set system and \(w \in \mathbb{R}_+^E\) be a weight vector.

Recall greedy algorithm: Set \(A = \emptyset\), and repeatedly choose \(y \in E \setminus A\) such that \(A \cup \{y\} \in \mathcal{I}\) with \(w(y)\) as large as possible, stopping when no such \(y\) exists.

For a matroid, we saw that independence system \((E, \mathcal{I})\) is a matroid iff for each weight function \(w \in \mathbb{R}_+^E\), the greedy algorithm leads to a set \(I \in \mathcal{I}\) of maximum weight \(w(I)\).

Stated succinctly, considering \(\max \{w(I) : I \in \mathcal{I}\}\), then \((E, \mathcal{I})\) is a matroid iff greedy works for this maximization.

Can we also characterize a polymatroid in this way?

That is, if we consider \(\max \{wx : x \in P_f^+\}\), where \(P_f^+\) represents the “independent vectors”, is it the case that \(P_f^+\) is a polymatroid iff greedy works for this maximization?

Can we, ultimately, even relax things so that \(w \in \mathbb{R}^E\)?
What is the greedy solution in this setting, when \( w \in \mathbb{R}^E \)?

Sort elements of \( E \) w.r.t. \( w \) so that, w.l.o.g.
\[
E = (e_1, e_2, \ldots, e_m) \text{ with } w(e_1) \geq w(e_2) \geq \cdots \geq w(e_m).
\]

Let \( k + 1 \) be the first point (if any) at which we are non-positive, i.e.,
\[
w(e_k) > 0 \text{ and } 0 \geq w(e_{k+1}).
\]

Next define partial accumulated sets \( E_i \), for \( i = 0 \ldots m \), we have w.r.t. the above sorted order:
\[
E_i \overset{\text{def}}{=} \{e_1, e_2, \ldots e_i\} \quad (12.22)
\]

(note \( E_0 = \emptyset \), \( f(E_0) = 0 \), and \( E \) and \( E_i \) is always sorted w.r.t \( w \)).

The greedy solution is the vector \( x \in \mathbb{R}_+^E \) with elements defined as:
\[
x(e_1) \overset{\text{def}}{=} f(E_1) = f(e_1) = f(e_1|E_0) = f(e_1|\emptyset) \quad (12.23)
\]
\[
x(e_i) \overset{\text{def}}{=} f(E_i) - f(E_{i-1}) = f(e_i|E_{i-1}) \text{ for } i = 2 \ldots k \quad (12.24)
\]
\[
x(e_i) \overset{\text{def}}{=} 0 \text{ for } i = k + 1 \ldots m = |E| \quad (12.25)
\]
Theorem 12.2.2

*The vector* \( x \in \mathbb{R}_+^E \) *as previously defined using the greedy algorithm maximizes* \( wx \) *over* \( P_f^+ \), *with* \( w \in \mathbb{R}_+^E \), *if* \( f \) *is submodular.*

Proof.

- Consider the LP strong duality equation:

\[
\max (wx : x \in P_f^+) = \min \left( \sum_{A \subseteq E} y_A f(A) : y \in \mathbb{R}_+^{2^E}, \sum_{A \subseteq E} y_A 1_A \geq w \right)
\]  
(12.21)

- Sort \( E \) by \( w \) descending, and define the following vector \( y \in \mathbb{R}_+^{2^E} \) as

\[
y_{Ei} \leftarrow w(e_i) - w(e_{i+1}) \text{ for } i = 1 \ldots (m - 1), \tag{12.22}
\]

\[
y_E \leftarrow w(e_m), \text{ and } \tag{12.23}
\]

\[
y_A \leftarrow 0 \text{ otherwise} \tag{12.24}
\]
Polymatroidal polyhedron and greedy

Thus, restating the above results into a single complete theorem, we have a result very similar to what we saw for matroids (i.e., Theorem 9.4.1)

**Theorem 12.2.2**

If $f : 2^E \to \mathbb{R}_+$ is given, and $P$ is a polytope in $\mathbb{R}^E_+$ of the form $P = \{ x \in \mathbb{R}^E_+ : x(A) \leq f(A), \forall A \subseteq E \}$, then the greedy solution to the problem $\max (w^\top x : x \in P)$ is $\forall w$ optimum iff $f$ is monotone non-decreasing submodular (i.e., iff $P$ is a polymatroid).
Multiple Polytopes associated with arbitrary $f$

- Given an arbitrary submodular function $f : 2^V \rightarrow \mathbb{R}$ (not necessarily a polymatroid function, so it need not be positive, monotone, etc.).
Multiple Polytopes associated with arbitrary $f$

- Given an arbitrary submodular function $f : 2^V \rightarrow \mathbb{R}$ (not necessarily a polymatroid function, so it need not be positive, monotone, etc.).
- If $f(\emptyset) \neq 0$, can set $f'(A) = f(A) - f(\emptyset)$ without destroying submodularity. This does not change any minima, (i.e., $\arg\min_A f(A) = \arg\min_A f'(A)$) so assume all functions are normalized $f(\emptyset) = 0$.

Note that due to constraint $x(\emptyset) \leq f(\emptyset)$, we must have $f(\emptyset) \geq 0$ since if not (i.e., if $f(\emptyset) < 0$), then $P_f^+$ doesn’t exist.

Another form of normalization can do is:

$$f'(A) = \begin{cases} f(A) & \text{if } A \neq \emptyset \\ 0 & \text{if } A = \emptyset \end{cases} \quad (12.1)$$

This preserves submodularity due to $f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$, and if $A \cap B = \emptyset$ then r.h.s. only gets smaller when $f(\emptyset) \geq 0$. 

Multiple Polytopes associated with arbitrary $f$

- Given an arbitrary submodular function $f : 2^V \rightarrow R$ (not necessarily a polymatroid function, so it need not be positive, monotone, etc.).
- If $f(\emptyset) \neq 0$, can set $f'(A) = f(A) - f(\emptyset)$ without destroying submodularity. This does not change any minima, (i.e., $\text{argmin}_A f(A) = \text{argmin}_A f'(A)$) so assume all functions are normalized $f(\emptyset) = 0$.
- We can define several polytopes:

\[
P_f = \left\{ x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E \right\} \quad (12.1)
\]
\[
P_f^+ = P_f \cap \left\{ x \in \mathbb{R}^E : x \geq 0 \right\} \quad (12.2)
\]
\[
B_f = P_f \cap \left\{ x \in \mathbb{R}^E : x(E) = f(E) \right\} \quad (12.3)
\]
Multiple Polytopes associated with arbitrary $f$

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- We can define several polytopes:

$$P_f = \{x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E\}$$  \hspace{1cm} (12.1)

$$P_f^+ = P_f \cap \{x \in \mathbb{R}^E : x \geq 0\}$$  \hspace{1cm} (12.2)

$$B_f = P_f \cap \{x \in \mathbb{R}^E : x(E) = f(E)\}$$  \hspace{1cm} (12.3)

- $P_f$ is what is sometimes called the extended polytope (sometimes notated as $EP_f$).
Multiple Polytopes associated with arbitrary $f$

- Given an arbitrary submodular function $f : 2^V \rightarrow R$ (not necessarily a polymatroid function, so it need not be positive, monotone, etc.).
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  $P_f = \{ x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E \}$ \hspace{1cm} (12.1)

  $P_f^+ = P_f \cap \{ x \in \mathbb{R}^E : x \geq 0 \}$ \hspace{1cm} (12.2)

  $B_f = P_f \cap \{ x \in \mathbb{R}^E : x(E) = f(E) \}$ \hspace{1cm} (12.3)

- $P_f$ is what is sometimes called the extended polytope (sometimes notated as $EP_f$).
- $P_f^+$ is $P_f$ restricted to the positive orthant.
Multiple Polytopes associated with arbitrary $f$

- Given an arbitrary submodular function $f : 2^V \rightarrow \mathbb{R}$ (not necessarily a polymatroid function, so it need not be positive, monotone, etc.).
- If $f(\emptyset) \neq 0$, can set $f'(A) = f(A) - f(\emptyset)$ without destroying submodularity. This does not change any minima, (i.e., $\text{argmin}_A f(A) = \text{argmin}_A f'(A)$) so assume all functions are normalized $f(\emptyset) = 0$.
- We can define several polytopes:

  \[ P_f = \{ x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E \} \tag{12.1} \]
  \[ P_f^+ = P_f \cap \{ x \in \mathbb{R}^E : x \geq 0 \} \tag{12.2} \]
  \[ B_f = P_f \cap \{ x \in \mathbb{R}^E : x(E) = f(E) \} \tag{12.3} \]

- $P_f$ is what is sometimes called the extended polytope (sometimes notated as $EP_f$).
- $P_f^+$ is $P_f$ restricted to the positive orthant.
- $B_f$ is called the base polytope, analogous to the base in matroid.
Multiple Polytopes in 2D associated with \( f \)

\[
P_f^+ = P_f \cap \{ x \in \mathbb{R}^E : x \geq 0 \} \quad (12.4)
\]

\[
P_f = \{ x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E \} \quad (12.5)
\]

\[
B_f = P_f \cap \{ x \in \mathbb{R}^E : x(E) = f(E) \} \quad (12.6)
\]
Multiple Polytopes in 2D associated with $f$

$$P_f^+ = P_f \cap \{ x \in \mathbb{R}^E : x \geq 0 \} \quad (12.4)$$

$$P_f = \{ x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E \} \quad (12.5)$$

$$B_f = P_f \cap \{ x \in \mathbb{R}^E : x(E) = f(E) \} \quad (12.6)$$
Possible Polytopes

Multiple Polytopes in 2D associated with \( f \)

\[ P_f^+ = P_f \cap \{ x \in \mathbb{R}^E : x \geq 0 \} \]  
\[ P_f = \{ x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E \} \]  
\[ B_f = P_f \cap \{ x \in \mathbb{R}^E : x(E) = f(E) \} \]
Possible Polytopes
Extreme Points
Polymatroids, Greedy, and Cardinality Constrained Maximization

Base Polytope in 3D

\[ P_f = \{ x \in \mathbb{R}^E : x(S) \leq f(S), \forall S \subseteq E \} \] (12.7)

\[ B_f = P_f \cap \{ x \in \mathbb{R}^E : x(E) = f(E) \} \] (12.8)
A polymatroid function’s polyhedron is a polymatroid.

**Theorem 12.3.1**

Let $f$ be a submodular function defined on subsets of $E$. For any $x \in \mathbb{R}^E$, we have:

$$\text{rank}(x) = \max (y(E) : y \leq x, y \in P_f) = \min (x(A) + f(E \setminus A) : A \subseteq E)$$  \hspace{1cm} (12.9)

Essentially the same theorem as Theorem 10.4.1, but note $P_f$ rather than $P_f^+$. Taking $x = 0$ we get:

**Corollary 12.3.2**

Let $f$ be a submodular function defined on subsets of $E$. We have:

$$\text{rank}(0) = \max (y(E) : y \leq 0, y \in P_f) = \min (f(A) : A \subseteq E)$$  \hspace{1cm} (12.10)
Proof of Theorem 12.3.1

Proof Thm 12.3.1: \( \max \{ y(E) : y \leq x, y \in P_f \} = \min \{ x(A) + f(E \setminus A) : A \subseteq E \} \).

- Let \( y^\star \) be optimal solution of the l.h.s. and let \( A \subseteq E \) be any subset.
Proof of Theorem 12.3.1

**Proof Thm 12.3.1:**\[
\max (y(E) : y \leq x, y \in P_f) = \min (x(A) + f(E \setminus A) : A \subseteq E).
\]

- Let \( y^* \) be optimal solution of the l.h.s. and let \( A \subseteq E \) be any subset.

- Then \( y^*(E) = y^*(A) + y^*(E \setminus A) \leq f(A) + x(E \setminus A) \) since if \( y^* \in P_f \), \( y^*(A) \leq f(A) \) and since \( y^* \leq x \), \( y^*(E \setminus A) \leq x(E \setminus A) \). This is a form of weak duality.
Proof of Theorem 12.3.1

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- For any \( e \in E \), if \( y^*(e) < x(e) \), must be some reason other than the constraint \( y^* \leq x \), namely it must be that \( \exists T \in D(y^*) \) with \( e \in T \) (i.e., \( e \) is a member of at least one of the tight sets).
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- For any \( e \in E \), if \( y^*(e) < x(e) \), must be some reason other than the constraint \( y^* \leq x \), namely it must be that \( \exists T \in D(y^*) \) with \( e \in T \) (i.e., \( e \) is a member of at least one of the tight sets). I.e., given \( e \notin \text{sat}(y^*) \), then \( y^*(A) < f(A) \forall A \ni e \) including \( \{e\} \), hence \( x(e) < f(e) \).
  Conversely, \( e \in \text{sat}(y^*) \) means \( y^*(T) = f(T) \) for some \( T \in D(y^*) \).
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Let $y^*$ be optimal solution of the l.h.s. and let $A \subseteq E$ be any subset.

Then $y^*(E) = y^*(A) + y^*(E \setminus A) \leq f(A) + x(E \setminus A)$ since if $y^* \in P_f$, $y^*(A) \leq f(A)$ and since $y^* \leq x$, $y^*(E \setminus A) \leq x(E \setminus A)$. This is a form of weak duality.

For any $e \in E$, if $y^*(e) < x(e)$, must be some reason other than the constraint $y^* \leq x$, namely it must be that $\exists T \in D(y^*)$ with $e \in T$ (i.e., $e$ is a member of at least one of the tight sets). I.e., given $e \notin \text{sat}(y^*)$, then $y^*(A) < f(A) \forall A \ni e$ including $\{e\}$, hence $x(e) < f(e)$.

Conversely, $e \in \text{sat}(y^*)$ means $y^*(T) = f(T)$ for some $T \in D(y^*)$.

Hence, for all $e \notin \text{sat}(y^*)$ we have $y^*(e) = x(e)$, and moreover $y^*(\text{sat}(y^*)) = f(\text{sat}(y^*))$ by definition.
Proof of Theorem 12.3.1

Proof Thm 12.3.1: \( \max (y(E) : y \leq x, y \in P_f) = \min (x(A) + f(E \setminus A) : A \subseteq E) \).

- Let \( y^* \) be optimal solution of the l.h.s. and let \( A \subseteq E \) be any subset.
- Then \( y^*(E) = y^*(A) + y^*(E \setminus A) \leq f(A) + x(E \setminus A) \) since if \( y^* \in P_f \), \( y^*(A) \leq f(A) \) and since \( y^* \leq x \), \( y^*(E \setminus A) \leq x(E \setminus A) \). This is a form of weak duality.
- For any \( e \in E \), if \( y^*(e) < x(e) \), must be some reason other than the constraint \( y^* \leq x \), namely it must be that \( \exists T \in \mathcal{D}(y^*) \) with \( e \in T \) (i.e., \( e \) is a member of at least one of the tight sets). I.e., given \( e \notin \text{sat}(y^*) \), then \( y^*(A) < f(A) \forall A \ni e \) including \( \{e\} \), hence \( x(e) < f(e) \).
  Conversely, \( e \in \text{sat}(y^*) \) means \( y^*(T) = f(T) \) for some \( T \in \mathcal{D}(y^*) \).
- Hence, for all \( e \notin \text{sat}(y^*) \) we have \( y^*(e) = x(e) \), and moreover \( y^*(\text{sat}(y^*)) = f(\text{sat}(y^*)) \) by definition.
- **Thus** \( y^*(\text{sat}(y^*)) + y^*(E \setminus \text{sat}(y^*)) = f(\text{sat}(y^*)) + x(E \setminus \text{sat}(y^*)) \), strong duality, showing that the two sides are equal for \( y^* \).
In Theorem 11.4.1 (i.e., greedy solution in $P_f^+$), we can relax $P_f^+$ to $P_f$ (prime and dual feasibility still hold as does strong duality).
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The proof, that is, shows that $x \in P_f$, not just $P_f^+$. 
Greedy and $P_f$

- In Theorem 11.4.1 (i.e., greedy solution in $P_f^+$), we can relax $P_f^+$ to $P_f$ (prime and dual feasibility still hold as does strong duality).
- The proof, that is, shows that $x \in P_f$, not just $P_f^+$.
- If $\exists e$ such that $w(e) < 0$ then $\max(wx : x \in P_f) = \infty$ since we can let $x_e \to \infty$, unless we ignore the negative elements or assume $w \geq 0$. 
In Theorem 11.4.1 (i.e., greedy solution in $P_f^+$), we can relax $P_f^+$ to $P_f$ (prime and dual feasibility still hold as does strong duality).

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If $\exists e$ such that $w(e) < 0$ then $\max(wx : x \in P_f) = \infty$ since we can let $x_e \rightarrow \infty$, unless we ignore the negative elements or assume $w \geq 0$.

Moreover, in either $P_f$, or $P_f^+$ case, since the greedy constructed an $x$ has $x(E) = f(E)$, we have that the greedy $x \in B_f$. 
In Theorem 11.4.1 (i.e., greedy solution in $P_f^+$), we can relax $P_f^+$ to $P_f$ (prime and dual feasibility still hold as does strong duality).

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Moreover, in either $P_f$, or $P_f^+$ case, since the greedy constructed an $x$ has $x(E) = f(E)$, we have that the greedy $x \in B_f$.

In fact, we will see, in the next section, that the greedy $x$ is a vertex of $B_f$. 
Recall that Theorem 10.4.1 states that
\[
\max \left( y(E) : y \leq x, y \in P_f^+ \right) = \min \left( x(A) + f(E \setminus A) : A \subseteq E \right)
\]
Recall that Theorem 10.4.1 states that
\[
\max \left( y(E) : y \leq x, y \in P_f^+ \right) = \min \left( x(A) + f(E \setminus A) : A \subseteq E \right)
\]

Theorem 11.4.1 states that greedy algorithm maximizes \( wx \) over \( P_f^+ \)
for \( w \in \mathbb{R}^E_+ \) with \( f \) being submodular.
Greedy and $P_f$

- Recall that Theorem 10.4.1 states that
  \[
  \max \left( y(E) : y \leq x, y \in P_f^+ \right) = \min \left( x(A) + f(E \setminus A) : A \subseteq E \right)
  \]

- Theorem 11.4.1 states that greedy algorithm maximizes $wx$ over $P_f^+$ for $w \in \mathbb{R}_{+}^E$ with $f$ being submodular.

- Above implies that Theorem 11.4.1 can be generalized to over $P_f$ and that greedy solution gives a point in $B_f$, even for arbitrary finite $w$. 
Polymatroid extreme points

- The greedy algorithm does more than solve $\max(wx : x \in P_f^+)$. We can use it to generate vertices of polymatroidal polytopes.
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![3D Diagram](image-url)
Polymatroid extreme points

Since \( w \in \mathbb{R}^E_+ \) is arbitrary, it may be that any \( e \in E \) is max (i.e., is such that \( w(e) > w(e') \) for \( e' \in E \setminus \{e\} \)).
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- Recall, base polytope defined as the extreme face of \( P_f \). I.e.,

\[
B_f = P_f \cap \left\{ x \in \mathbb{R}_+^E : x(E) = f(E) \right\}
\]  \hspace{1cm} (12.11)

Also, intuitively, we can continue advancing along the skeletal edges of the polytope to reach any other vertex, given the appropriate ordering. If we advance in all dimensions, we'll reach a vertex in \( B_f \), and if we advance only in some dimensions, we'll reach a vertex in \( P_f \cap \{ x \in \mathbb{R}_+^E : x(A) = 0 \} \) for some \( A \).
Polymatroid extreme points

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- We formalize this next:
Polymatroid extreme points

Given any arbitrary order of $E = (e_1, e_2, \ldots, e_m)$, define $E_i = (e_1, e_2, \ldots, e_i)$.
Polymatroid extreme points

- Given any arbitrary order of $E = (e_1, e_2, \ldots, e_m)$, define $E_i = (e_1, e_2, \ldots, e_i)$.
- As before, a vector $x$ is generated by $E_i$ using the greedy procedure as follows

\[
x(e_1) = f(E_1) = f(e_1) \tag{12.12}
\]
\[
x(e_j) = f(E_j) - f(E_{j-1}) = f(e_j | E_{j-1}) \text{ for } 2 \leq j \leq i \tag{12.13}
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  \end{align}

- An extreme point of $P_f$ is a point that is not a convex combination of two other distinct points in $P_f$. Equivalently, an extreme point corresponds to setting certain inequalities in the specification of $P_f$ to be equalities, so that there is a unique single point solution.
Polymatroid extreme points

Theorem 12.4.1

For a given ordering $E = (e_1, \ldots, e_m)$ of $E$ and a given $E_i = (e_1, \ldots, e_i)$ and $x$ generated by $E_i$ using the greedy procedure ($x(e_i) = f(e_i | E_{i-1})$), then $x$ is an extreme point of $P_f$ when $f$ is submodular.
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Proof.

- We already saw that $x \in P_f$ (Theorem 11.4.1).
Polymatroid extreme points

**Theorem 12.4.1**

For a given ordering $E = (e_1, \ldots, e_m)$ of $E$ and a given $E_i = (e_1, \ldots, e_i)$ and $x$ generated by $E_i$ using the greedy procedure ($x(e_i) = f(e_i | E_{i-1})$), then $x$ is an extreme point of $P_f$ when $f$ is submodular.

**Proof.**

- We already saw that $x \in P_f$ (Theorem 11.4.1).
- To show that $x$ is an extreme point of $P_f$, note that it is the unique solution of the following system of equations

  $$x(E_j) = f(E_j) \text{ for } 1 \leq j \leq i \leq m \quad (12.14)$$
  $$x(e) = 0 \text{ for } e \in E \setminus E_i \quad (12.15)$$

  There are $i \leq m$ equations and $i \leq m$ unknowns, and simple Gaussian elimination gives us back the $x$ constructed via the Greedy algorithm!!
Polymatroid extreme points

- As an example, we have $x(E_1) = x(e_1) = f(e_1)$
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Polymatroid extreme points

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\[ x(e_2) = f(e_1, e_2) - x(e_1) = f(e_1, e_2) - f(e_1) = f(e_2 | e_1). \]

\[ x(E_3) = x(e_1) + x(e_2) + x(e_3) = f(e_1, e_2, e_3) \quad \text{so} \]
\[ x(e_3) = f(e_1, e_2, e_3) - x(e_2) - x(e_1) = f(e_1, e_2, e_3) - f(e_1, e_2) = f(e_3 | e_1, e_2) \]
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- And so on . . . , but we see that this is just Gaussian elimination.
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- And so on . . . , but we see that this is just Gaussian elimination.
- Also, since $x \in P_f$, for each $i$, we see that,

\[
x(E_j) = f(E_j) \quad \text{for } 1 \leq j \leq i \tag{12.16}
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\[
x(A) \leq f(A), \forall A \subseteq E \tag{12.17}
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Polymatroid extreme points

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- Also, since $x \in P_f$, for each $i$, we see that,
  \[ x(E_j) = f(E_j) \quad \text{for } 1 \leq j \leq i \]  \hspace{1cm} (12.16)
  \[ x(A) \leq f(A), \forall A \subseteq E \]  \hspace{1cm} (12.17)
- Thus, the greedy procedure provides a modular function lower bound on $f$ that is tight on all points $E_i$ in the order. This can be useful in its own right, as it provides subgradients and subdifferential structure.
Polymatroid extreme points

some examples
Polymatroid extreme points

Moreover, we have (and will ultimately prove)

**Corollary 12.4.2**

*If* $x$ *is an extreme point of* $P_f$ *and* $B \subseteq E$ *is given such that*

$$\text{supp}(x) = \{e \in E : x(e) \neq 0\} \subseteq B \subseteq \bigcup (A : x(A) = f(A)) = \text{sat}(x),$$

*then* $x$ *is generated using greedy by some ordering of* $B$. 

Polymatroid extreme points

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- **Note,** $\text{sat}(x) = \text{cl}(x) = \bigcup(A : x(A) = f(A))$ is also called the closure of $x$ (recall that sets $A$ such that $x(A) = f(A)$ are called tight, and such sets are closed under union and intersection, as seen in Lecture 10, Theorem 10.4.3)
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Polymatroid extreme points

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- Also, $\text{supp}(x) = \{e \in E : x(e) \neq 0\}$ is called the support of $x$.

- For arbitrary $x$, $\text{supp}(x)$ is not necessarily tight, but for an extreme point, $\text{supp}(x)$ is.
Recall
\[ f(e|A) = f(A+e) - f(A) \]

Notice how submodularity,
\[ f(e|B) \leq f(e|A) \]
for \( A \subseteq B \), defines the shape of the polytope.

In fact, we have strictness here
\[ f(e|B) < f(e|A) \]
for \( A \subset B \).

Also, consider how the greedy algorithm proceeds along the edges of the polytope.
Polymatroid with labeled edge lengths

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Intuition: why greedy works with polymatroids

- Given $w$, the goal is to find
  
  $x = (x(e_1), x(e_2))$
  
  that maximizes
  
  $x^T w = x(e_1)w(e_1) + x(e_2)w(e_2)$.

- If $w(e_2) > w(e_1)$ the upper extreme point indicated maximizes $x^T w$ over $x \in P_f^+$. 

- If $w(e_2) < w(e_1)$ the lower extreme point indicated maximizes $x^T w$ over $x \in P_f^+$. 
Submodular maximization is quite useful.
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Applications: sensor placement, facility location, document summarization, or any kind of covering problem (choose a small set of elements that cover some domain as much as possible).
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Thus, when we do monotone submodular maximization we find the maximum under some constraint.

There is also a sort of dual problem that is often considered together with max, and those are minimum cover problems (to be defined).
The Set Cover Problem

- Let $E$ be a ground set and let $E_1, E_2, \ldots, E_m$ be a set of subsets.
The Set Cover Problem

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- Let $V = \{1, 2, \ldots, m\}$ be the set of integers.
The Set Cover Problem

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- Let $V = \{1, 2, \ldots, m\}$ be the set of integers.
- Define $f : 2^V \rightarrow \mathbb{Z}_+$ as $f(X) = \left| \bigcup_{v \in X} E_v \right|$. 

The problem asks for the smallest subset $X$ of $V$ such that $f(X) = |E|$ (smallest subset of the subsets of $E$) where $E$ is still covered. 

We might wish to use a more general modular function $m(X)$ rather than cardinality $|X|$. This problem is NP-hard, and Feige in 1998 showed that it cannot be approximated with a ratio better than $(1 - \epsilon) \log n$ unless NP is slightly superpolynomial ($n^O(\log \log n)$).
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$$\min |X| \text{ subject to } f(X) \geq |E|$$ (12.18)

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What About Non-monotone

- So even simple case of cardinality constrained submodular function maximization is NP-hard.
- This will be true of most submodular max (and related) problems.
- Hence, the only hope is approximation algorithms. Question is, what is the tradeoff between running time and approximation quality, and is it possible to get tight bounds (i.e., an algorithm that achieves an approximation ratio, and a proof that one can’t do better than that unless some extremely unlike event were to be true, such as P=NP).
The Max $k$-Cover Problem

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The Max $k$-Cover Problem

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The Max $k$-Cover Problem

- Let $E$ be a ground set and let $E_1, E_2, \ldots, E_m$ be a set of subsets.
- Let $V = \{1, 2, \ldots, m\}$ be the set of integers.
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- Then $f$ is the set cover function. As we saw, $f$ is monotone submodular (a polymatroid).
The Max $k$-Cover Problem

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The max $k$ cover problem asks, given a $k$, what sized $k$ set of sets $X$ can we choose that covers the most? I.e., that maximizes $f(X)$ as in:

$$\max f(X) \text{ subject to } |X| \leq k \quad (12.19)$$
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$$\max f(X) \text{ subject to } |X| \leq k$$  \hspace{1cm} (12.19)

This problem is NP-hard, and Feige in 1998 showed that it cannot be approximated with a ratio better than $(1 - 1/e)$. 
Now we are given an arbitrary polymatroid function $f$. 
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An important result by Nemhauser et. al. (1978) states that for normalized \( (f(\emptyset) = 0) \) monotone submodular functions (i.e., polymatroids) can be approximately maximized using a simple greedy algorithm.
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An important result by Nemhauser et. al. (1978) states that for normalized ($f(\emptyset) = 0$) monotone submodular functions (i.e., polymatroids) can be approximately maximized using a simple greedy algorithm.

Starting with $S_0 = \emptyset$, we repeat the following greedy step for $i = 0 \ldots (k - 1)$:

$$S_{i+1} = S_i \cup \left\{ \arg\max_{v \in V \setminus S_i} f(S_i \cup \{v\}) \right\} \quad (12.20)$$
A bit more precisely:

**Algorithm 1: The Greedy Algorithm**

1. Set $S_0 \leftarrow \emptyset$;
2. for $i \leftarrow 0 \ldots |E| - 1$ do
   3. Choose $v_i$ as follows:
      \[
      v_i \in \arg\max_{v \in V \backslash S_i} f(\{v\}|S_i) = \arg\max_{v \in V \backslash S_i} f(S_i \cup \{v\}) ;
      \]
   4. Set $S_{i+1} \leftarrow S_i \cup \{v_i\}$ ;
• This algorithm has a guarantee
This algorithm has a guarantee

**Theorem 12.5.1**

*Given a polymatroid function $f$, the above greedy algorithm returns sets $S_i$ such that for each $i$ we have $f(S_i) \geq (1 - 1/e) \max_{|S| \leq i} f(S)$.*
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To approximately find $A^* \in \arg\max \{f(A) : |A| \leq k\}$, we repeat the greedy step until $k = i + 1$:
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**Theorem 12.5.1**

*Given a polymatroid function \( f \), the above greedy algorithm returns sets \( S_i \) such that for each \( i \) we have \( f(S_i) \geq (1 - 1/e) \max_{|S| \leq i} f(S) \).*

- To approximately find \( A^* \in \arg\max \{f(A) : |A| \leq k\} \), we repeat the greedy step until \( k = i + 1 \):
- Again, since this generalizes max \( k \)-cover, Feige (1998) showed that this can’t be improved. Unless \( P = NP \), no polynomial time algorithm can do better than \((1 - 1/e + \epsilon)\) for any \( \epsilon > 0 \).
The Greedy Algorithm: $1 - 1/e$ intuition.

- At step $i < k$, greedy chooses $v_i$ to maximize $f(v|S_i)$.
The Greedy Algorithm: $1 - 1/e$ intuition.

- At step $i < k$, greedy chooses $v_i$ to maximize $f(v|S_i)$.
- Let $S^*$ be optimal solution (of size $k$) and $\text{OPT} = f(S^*)$. 

Equation (12.30) will show that Equation (12.21) \[ \text{OPT} - f(S^* + 1) \leq (1 - 1/k)(\text{OPT} - f(S^*)) \Rightarrow \text{OPT} \leq 1/e \text{OPT} \Rightarrow \text{OPT}(1 - 1/e) \leq f(S^*) \]
The Greedy Algorithm: $1 - 1/e$ intuition.

- At step $i < k$, greedy chooses $v_i$ to maximize $f(v|S_i)$.
- Let $S^*$ be optimal solution (of size $k$) and $\text{OPT} = f(S^*)$. By submodularity, we will show:

$$\exists v \in V \setminus S_i : f(v|S_i) = f(S_i + v|S_i) \geq \frac{1}{k}(\text{OPT} - f(S_i))$$  \hspace{1cm} (12.21)
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![Graph showing the trend of $(1 - \frac{1}{k})^k$ as $k$ increases](image)
The Greedy Algorithm: $1 - 1/e$ intuition.

- At step $i < k$, greedy chooses $v_i$ to maximize $f(v|S_i)$.
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$$OPT - f(S_{i+1}) \leq (1 - 1/k)(OPT - f(S_i))$$

$$\Rightarrow \quad OPT - f(S_k) \leq (1 - 1/k)^k OPT$$

$$\leq 1/eOPT$$

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The Greedy Algorithm: $1 - 1/e$ intuition.

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$$\begin{align*}
OPT - f(S_{i+1}) &\leq (1 - 1/k)(OPT - f(S_i)) \\
&\Rightarrow OPT - f(S_k) \\
&\leq (1 - 1/k)^k OPT \\
&\leq 1/eOPT \\
&\Rightarrow OPT(1 - 1/e) \leq f(S_k)
\end{align*}$$
Cardinality Constrained Polymatroid Max Theorem

Theorem 12.5.2 (Nemhauser et al. 1978)

Given non-negative monotone submodular function \( f : 2^V \rightarrow \mathbb{R}_+ \), define \( \{S_i\}_{i \geq 0} \) to be the chain formed by the greedy algorithm (Eqn. (12.20)). Then for all \( k, \ell \in \mathbb{Z}_{++} \), we have:

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f(S_\ell) \geq (1 - e^{-\ell/k}) \max_{S : |S| \leq k} f(S)
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and in particular, for \( \ell = k \), we have

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- $k$ is size of optimal set, i.e., $\text{OPT} = f(S^*)$ with $|S^*| = k$
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- Bound is how well does \( S_\ell \) (of size \( \ell \)) do relative to \( S^* \), the optimal set of size \( k \).
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- Intuitively, bound should get worse when \( \ell < k \) and get better when \( \ell > k \).
Cardinality Constrained Polymatroid Max Theorem

Proof of Theorem 12.5.2.

Let \( S^* = (v^*_1, v^*_2, \ldots, v^*_k) \) be the greedy order chain chosen by the algorithm, for \( i \in \{1, 2, \ldots, \ell\} \).

Then the following inequalities (on the next slide) follow:
Proof of Theorem 12.5.2.

- Fix $\ell$ (number of items greedy will chose) and $k$ (size of optimal set to compare against).
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Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 12.5.2 cont.
Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 12.5.2 cont.

- For all \( i < \ell \), we have

\[
f(S^*)
\]
Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 12.5.2 cont.

- For all \( i < \ell \), we have
  \[
  f(S^*) \leq f(S^* \cup S_i)
  \]
... proof of Theorem 12.5.2 cont.

For all $i < \ell$, we have

$$f(S^*) \leq f(S^* \cup S_i) = f(S_i) + f(S^*|S_i) \tag{12.23}$$
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(12.23)

$$= f(S_i) + \sum_{j=1}^{k} f(v_j^*|S_i \cup \{v_1^*, v_2^*, \ldots, v_{j-1}^*\})$$

(12.24)
Cardinality Constrained Polymatroid Max Theorem

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\]

\[
    \leq f(S_i) + \sum_{v \in S^*} f(v|S_i) \tag{12.25}
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Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 12.5.2 cont.

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  \leq f(S_i) + \sum_{v \in S^*} f(v|S_i) \\
  \leq f(S_i) + \sum_{v \in S^*} f(v_{i+1}|S_i) = f(S_i) + \sum_{v \in S^*} f(S_{i+1}|S_i) 
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\[ f(S^*) \leq f(S^* \cup S_i) = f(S_i) + f(S^* | S_i) \] (12.23)

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\[ \leq f(S_i) + \sum_{v \in S^*} f(v_{i+1} | S_i) = f(S_i) + \sum_{v \in S^*} f(S_{i+1} | S_i) \] (12.26)

\[ = f(S_i) + kf(S_{i+1} | S_i) \] (12.27)
Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 12.5.2 cont.

For all \( i < \ell \), we have

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  f(S^*) \leq f(S^* \cup S_i) = f(S_i) + f(S^*|S_i) \tag{12.23}
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\]

\[
  = f(S_i) + kf(S_{i+1}|S_i) \tag{12.27}
\]

Therefore, we have Equation 12.21, i.e.,:

\[
  f(S^*) - f(S_i) \leq kf(S_{i+1}|S_i) = k(f(S_{i+1}) - f(S_i)) \tag{12.28}
\]
Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 12.5.2 cont.
Define gap $\delta_i \triangleq f(S^*) - f(S_i)$, so $\delta_i - \delta_{i+1} = f(S_{i+1}) - f(S_i)$.
Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 12.5.2 cont.

- Define gap $\delta_i \triangleq f(S^*) - f(S_i)$, so $\delta_i - \delta_{i+1} = f(S_{i+1}) - f(S_i)$, giving

$$\delta_i \leq k(\delta_i - \delta_{i+1})$$

(12.29)

or
Cardinality Constrained Polymatroid Max Theorem

...proof of Theorem 12.5.2 cont.

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$$\delta_{i+1} \leq (1 - \frac{1}{k})\delta_i$$

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Define gap $\delta_i \triangleq f(S^*) - f(S_i)$, so $\delta_i - \delta_{i+1} = f(S_{i+1}) - f(S_i)$, giving
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The relationship between $\delta_0$ and $\delta_{\ell}$ is then
$$\delta_{\ell} \leq (1 - \frac{1}{k})^\ell \delta_0 \tag{12.31}$$
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Now, $\delta_0 = f(S^*) - f(\emptyset) \leq f(S^*)$ since $f \geq 0$. 
... proof of Theorem 12.5.2 cont.

- Define gap $\delta_i \triangleq f(S^*) - f(S_i)$, so $\delta_i - \delta_{i+1} = f(S_{i+1}) - f(S_i)$, giving
  
  $$\delta_i \leq k(\delta_i - \delta_{i+1}) \quad (12.29)$$

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- The relationship between $\delta_0$ and $\delta_\ell$ is then

  $$\delta_\ell \leq (1 - \frac{1}{k})^\ell \delta_0 \quad (12.31)$$

- Now, $\delta_0 = f(S^*) - f(\emptyset) \leq f(S^*)$ since $f \geq 0$.

- Also, by variational bound $1 - x \leq e^{-x}$ for $x \in \mathbb{R}$, we have

  $$\delta_\ell \leq (1 - \frac{1}{k})^\ell \delta_0 \leq e^{-\ell/k} f(S^*) \quad (12.32)$$
Possible Polytopes

Extreme Points

Polymatroids, Greedy, and Cardinality Constrained Maximization

Cardinality Constrained Polymatroid Max Theorem

... proof of Theorem 12.5.2 cont.

When we identify $\delta_l = f(S^*) - f(S_\ell)$, a bit of rearranging then gives:

$$f(S_\ell) \geq (1 - e^{-\ell/k}) f(S^*)$$  \hspace{1cm} (12.33)

With $\ell = k$, when picking $k$ items, greedy gets $(1 - 1/e) \approx 0.6321$ bound. This means that if $S_k$ is greedy solution of size $k$, and $S^*$ is an optimal solution of size $k$, $f(S_k) \geq (1 - 1/e) f(S^*) \approx 0.6321 f(S^*)$.

What if we want to guarantee a solution no worse than $0.95 f(S^*)$ where $|S^*| = k$?

Set $0.95 = (1 - e^{-\ell/k})$, which gives $\ell = \lceil -k \ln(1 - 0.95) \rceil = 4k$. And $\lceil -\ln(1 - 0.999) \rceil = 7$.

So solution, in the worst case, quickly gets very good. Typical/practical case is much better.
... proof of Theorem 12.5.2 cont.

When we identify \( \delta_l = f(S^*) - f(S_l) \), a bit of rearranging then gives:

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When we identify $\delta_\ell = f(S^*) - f(S_\ell)$, a bit of rearranging then gives:

$$f(S_\ell) \geq (1 - e^{-\ell/k}) f(S^*) \quad (12.33)$$

With $\ell = k$, when picking $k$ items, greedy gets $(1 - 1/e) \approx 0.6321$ bound. This means that if $S_k$ is greedy solution of size $k$, and $S^*$ is an optimal solution of size $k$, $f(S_k) \geq (1 - 1/e)f(S^*) \approx 0.6321f(S^*)$. 
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Cardinality Constrained Polymatroid Max Theorem

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And \( \lceil -\ln(1 - 0.999) \rceil = 7 \).
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- So solution, in the worst case, quickly gets very good. Typical/practical case is much better.
Greedy running time

- Greedy computes a new maximum $n = |V|$ times, and each maximum computation requires $O(n)$ comparisons, leading to $O(n^2)$ computation for greedy.
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- This is called Minoux’s 1977 Accelerated Greedy strategy (and has been rediscovered a few times, e.g., “Lazy greedy”), and runs much faster while still producing same answer.
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- We describe it next:
Minoux’s Accelerated Greedy for Submodular Functions

- At stage $i$ in the algorithm, we have a set of gains $f(v|S_i)$ for all $v \notin S_i$. Store these values $\alpha_v \leftarrow f(v|S_i)$ in sorted priority queue.
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Prof. Jeff Bilmes
Minoux’s Accelerated Greedy for Submodular Functions

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Therefore, if we find a $v'$ such that $f(v'|S_{i+1}) \geq \alpha_v$ for all $v \neq v'$, then since

$$f(v'|S_{i+1}) \geq \alpha_v = f(v|S_i) \geq f(v|S_{i+1}) \quad (12.34)$$

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Strategy is: find the $\text{argmax}_{v' \in V \setminus S_{i+1}} \alpha_{v'}$, and then compute the real $f(v'|S_{i+1})$. If it is greater than all other $\alpha_v$’s then that’s the next greedy step. Otherwise, replace $\alpha_{v'}$ with its real value, resort ($O(\log n)$), and repeat.
Minoux’s Accelerated Greedy for Submodular Functions

- Minoux’s algorithm is exact, in that it has the same guarantees as does the $O(n^2)$ greedy Algorithm 4 (this means it will return either the same answers, or answers that have the $1 - 1/e$ guarantee).
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- When choosing a of size $k$, naïve greedy algorithm is $O(nk)$ but accelerated variant at the very best does $O(n + k)$, so this limits the speedup.
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- Can be used for “big data” sets (e.g., social networks, selecting blogs of greatest influence, document summarization, etc.).
Priority Queue

- Use a priority queue $Q$ as a data structure: operations include:

  - Insert an item $(v, \alpha)$ into queue, with $v \in V$ and $\alpha \in \mathbb{R}$.

    \[
    \text{insert}(Q, (v, \alpha)) \quad (12.35)
    \]

  - Pop the item $(v, \alpha)$ with maximum value $\alpha$ off the queue.

    \[
    (v, \alpha) \leftarrow \text{pop}(Q) \quad (12.36)
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  - Query the value of the max item in the queue $\max(Q) \in \mathbb{R}$.

    \[
    \max(Q) \quad (12.37)
    \]

  - On next slide, we call a popped item “fresh” if the value $(v, \alpha)$ popped has the correct value $\alpha = f(v|S_i)$. Use extra “bit” to store this info.

  - If a popped item is fresh, it must be the maximum — this can happen if, at a given iteration, $v$ was first popped and neither fresh nor maximum so placed back in the queue, and it then percolates back to the top at which point it is fresh — thereby avoiding extra queue check.
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Algorithm 2: Minoux's Accelerated Greedy Algorithm

1. Set $S_0 \leftarrow \emptyset$; $i \leftarrow 0$; Initialize priority queue $Q$;
2. for $v \in E$ do
   3. $\text{INSERT}(Q, f(v))$
3. repeat
   4. $(v, \alpha) \leftarrow \text{pop}(Q)$;
   5. if $\alpha$ not "fresh" then
      6. recompute $\alpha \leftarrow f(v | S_i)$
   7. if $(\text{popped } \alpha \text{ in line 5 was "fresh"}) \text{ OR } (\alpha \geq \max(Q))$ then
      8. Set $S_{i+1} \leftarrow S_i \cup \{v\}$;
      9. $i \leftarrow i + 1$
   10. else
      11. $\text{insert}(Q, (v, \alpha))$
   12. until $i = |E|$;
Given polymatroid $f$, goal is to find a covering set of minimum cost:

$$S^* \in \arg\min_{S \subseteq V} |S| \text{ such that } f(S) \geq \alpha$$

(12.38)

where $\alpha$ is a “cover” requirement.
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Normally take $\alpha = f(V)$ but defining $f'(A) = \min \{f(A), \alpha\}$ we can take any $\alpha$. Hence, we have equivalent formulation:

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\[ F41/45 \]
(Minimum) Submodular Set Cover

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- Note that this immediately generalizes standard set cover, in which case $f(A)$ is the cardinality of the union of sets indexed by $A$.

- Greedy Algorithm: Pick the first chain item $S_i$ chosen by aforementioned greedy algorithm such that $f(S_i) \geq \alpha$ and output that as solution.
For integer valued $f$, this greedy algorithm an $O(\log(\max_{s \in V} f(\{s\})))$ approximation. Let $S^*$ be optimal, and $S^G$ be greedy solution, then

$$|S^G| \leq |S^*| H(\max_{s \in V} f(\{s\})) = |S^*| O(\log_e(\max_{s \in V} f(\{s\}))) \quad (12.40)$$

where $H$ is the harmonic function, i.e., $H(d) = \sum_{i=1}^{d} (1/i)$.
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If $f$ is not integral value, then bounds we get are of the form:

$$|S^G| \leq |S^*| \left( 1 + \log_e \frac{f(V)}{f(V) - f(S_{T-1})} \right)$$

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where $S_T$ is the final greedy solution that occurs at step $T$. 
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Set cover is hard to approximate with a factor better than $(1 - \epsilon) \log \alpha$, where $\alpha$ is the desired cover constraint.
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- Submodular cover: min. $|S|$ s.t. $f(S) \geq \alpha$.
- Minoux's accelerated greedy trick.
The Greedy Algorithm: $1 - 1/e$ intuition.

- At step $i < k$, greedy chooses $v_i$ to maximize $f(v|S_i)$.
- Let $S^*$ be optimal solution (of size $k$) and $\text{OPT} = f(S^*)$. By submodularity, we will show:

$$\exists v \in V \setminus S_i : f(v|S_i) = f(S_i + v|S_i) \geq \frac{1}{k}(\text{OPT} - f(S_i)) \quad (12.21)$$

Equation (12.30) will show that Equation (12.21) $\Rightarrow$:

$$\text{OPT} - f(S_{i+1}) \leq (1 - 1/k)(\text{OPT} - f(S_i))$$

$\Rightarrow$ $\text{OPT} - f(S_k) \leq (1 - 1/k)^k \text{OPT}$

$\leq 1/e \text{OPT}$

$\Rightarrow$ $\text{OPT}(1 - 1/e) \leq f(S_k)$
Randomized greedy

How can we produce a randomized greedy strategy, one where each greedy sweep produces a set that, on average, has a $1 - \frac{1}{e}$ guarantee?

Suppose the following holds:

$$E[f(a_i + 1 | A_i)] \geq f(OPT) - f(A_i)$$  \hspace{1cm} (12.42)

where $A_i = (a_1, a_2, ..., a_i)$ are the first $i$ elements chosen by the strategy.

See problem 5, homework 4.
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